SYNCHRONIZED RECTIFYING CONTROLLER FOR A FORWARD

POWER CONVERTER

BACKGROUND OF THE INVENTION

Field of the Invention

[0001] The present invention relates to a pulse-width-modulation (PWM) forward

power converter. More particularly, the present invention relates to a forward power

converter employing a secondary controller to synchronously drive a pair of output

rectifiers.

Description of the Related Art

[0002] Power converters are widely used by various electronic products to convert

an AC input voltage into a DC supply voltage.

[0003] Various topologies such as flyback, forward, half-bridge, and full-bridge have

been developed for different power needs. In traditional power converters, diodes are

usually used as secondary rectifying components. In applications where high output

currents frequently occur, the high forward voltage drop across the diodes causes

significant power loss, which reduces power conversion efficiency. To avoid this

problem, some power supplies use MOSFETs having low on-state resistance, instead of

diodes. This substitution can reduce power consumption and improve power conversion

efficiency.

[0004] Some synchronized rectifying controllers sense the primary gate signal to

avoid cross-conduction from the secondary-side MOSFETs. This technique can reduce

propagation delay, but it requires using an opto-coupler or an additional transformer to

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maintain isolation between the primary-side and the secondary-side of the main transformer. This increases the cost and complexity of the circuit. Another drawback of this approach is that the circulated conduction losses increase under light-load condition. Such reversed inductor currents increase component stress and reduce power conversion efficiency.

[0005] Therefore, there is a need for a synchronized rectifying controller with a precise output voltage detection circuit.

SUMMARY OF THE INVENTION

[0006] A primary object of the present invention is to provide a forward power converter with a synchronized rectifying controller to control the rectifying MOSFETs of the forward power converter.

[0007] It is another object of the present invention to prevent cross-conduction between the rectifying MOSFETs.

[0008] It is a further object of the present invention to prevent reverse inductor currents. This reduces component stress and improves power conversion efficiency under light-load conditions. The forward power converter according to the present invention includes a current-sense mechanism to avoid reverse currents from the output inductor.

[0009] It is another object of the present invention to monitor the voltage from the secondary winding of the transformer. This reduces the cost and complexity of the detection circuit.

[0010] According to an aspect of the present invention, the synchronized rectifying controller according to the present invention can control two rectifying MOSFETs so

that the forward power converter can provide a clean output voltage. The forward power converter according to the present invention prevents cross-conduction of the rectifying MOSFETs by controlling the maximum on-time of a second rectifying MOSFET, in a manner that is programmable and precise. The synchronized rectifying controller according to the present invention determines the maximum on-time using a timing resistor coupled to a single-pulse generator.

[0011] It is to be understood that both the foregoing general descriptions and the following detailed descriptions are exemplary, and are intended to provide further explanation of the invention as claimed.

BRIEF DESCRIPTION OF THE DRAWINGS

- [0012] The accompanying drawings are included to provide a further understanding of the invention, and are incorporated in and constitute a part of this specification. The drawings illustrate embodiments of the invention and, together with the description, serve to explain the principles of the invention.
- [0013] FIG. 1 shows a schematic diagram of a prior-art forward power converter using diodes as rectifying components.
- [0014] FIG. 2A shows the circuit operation of a prior-art forward power converter while a primary-side MOSFET is turned on.
- [0015] FIG. 2B shows the circuit operation of a prior-art forward power converter while the primary-side MOSFET is turned off.
- [0016] FIG. 3 shows a schematic diagram of a prior-art forward power converter using MOSFETs as rectifying components.
- [0017] FIG. 4 shows a schematic diagram of a forward power converter including a

synchronized rectifying controller according to the present invention.

[0018] FIG. 5 shows a forward power converter including the synchronized rectifying controller according to a preferred embodiment of the present invention.

[0019] FIG. 6 shows the synchronized rectifying controller according to a preferred embodiment of the present invention.

[0020] FIG. 7 shows a single-pulse generator of the synchronized rectifying controller according to a preferred embodiment of the present invention.

[0021] FIG. 8 shows the timing diagram of the synchronized rectifying controller according to the present invention.

DESCRIPTION OF THE PREFERRED EMBODIMENTS

[0022] FIG. 1 shows a typical forward power converter. When a primary-side MOSFET 10 is turned on by a logic-high PWM signal, energy is transferred from the primary-side to the secondary-side of a transformer 11. As FIG. 2A shows, the voltage across a secondary winding of the transformer 11 will start to charge an output inductor 17 and an output capacitor 14 via a rectifying diode 12. Once the PWM signal drops to logic-low, as shown in FIG. 2B, the primary-side MOSFET 10 will be turned off and the output inductor 17 will begin to release its energy to the output capacitor 14 via a rectifying diode 13. However, the on-state voltage drop across the secondary-side rectifying diodes 12 and 13 causes significant power consumption, which reduces power conversion efficiency. In order to solve this problem, the secondary-side rectifying diodes can be replaced with MOSFETs. The parasitic diodes of the MOSFETs have low on-state voltage drops, so this technique can improve power conversion efficiency.

[0023] As FIG. 3 shows, a parasitic diode 19 of a MOSFET 15 and a parasitic diode

18 of a MOSFET 16 replace the rectifying diode 12 and the rectifying diode 13 shown in FIG. 1. By properly synchronizing the gate signals of the MOSFETs 15 and 16, the forward converter can produce the same output power while reducing power loss. To precisely synchronize the gate signals of the MOSFETs 15 and 16, it is necessary to accurately measure the PWM signal.

FIG. 4 shows a schematic circuit diagram of a forward power converter [0024] having a synchronized rectifying controller 30 according to the present invention. Referring to FIG. 4, the forward power converter comprises a transformer 11 having a primary winding connected to a primary circuit and a secondary winding connected to a secondary circuit. A primary-side MOSFET 10 is coupled to the primary winding of the transformer 11 to control power conduction. A detection diode 20 is connected between a positive end of the secondary winding of the transformer 11 and a detection input DET of the synchronized rectifying controller 30. An output inductor 17 is connected from the positive end of the secondary winding of the transformer 11 and a positive end of the power converter output. An output capacitor 14 is connected across the positive end of the power converter output and the ground reference. A gate of a MOSFET 15 is driven by a first output OUT1 of the synchronized rectifying controller 30. A gate of a MOSFET 16 is driven by a second output OUT2 of the synchronized rectifying controller 30. A drain of the MOSFET 15 is connected to a negative end of the secondary winding of the transformer 11. A source of the MOSFET 15 is connected to a source of the MOSFET 16. A drain of the MOSFET 16 is connected to the positive end of the secondary winding of the transformer 11. The source of the MOSFET 16 is connected to the ground reference via a current-sense mechanism 21.

[0025] The synchronized rectifying controller 30 has the detection input DET for

detecting the PWM signal from the voltage of the secondary winding. Once a logic-high signal is detected at the detection input **DET** via the detection diode **20**, the synchronized rectifying controller **30** will turn on the MOSFET **15** and the energy from the secondary winding will charge the output inductor **17** and the output capacitor **14** via the parasitic diode **19** of the MOSFET **15** during the conduction period. When the conduction period stops, the MOSFET **16** will be turned on and the energy stored in the output inductor **17** will be freewheeled into the output capacitor **14** via the parasitic diode **18** of the MOSFET **16**.

[0026] FIG. 5 shows the forward power converter according to one preferred embodiment the present invention. The current-sense mechanism 21 shown in FIG. 4 is composed of a first resistor 80 and a second resistor 81. The first resistor 80 is connected between the source of the MOSFET 16 and a positive-sense input S+ of the synchronized rectifying controller 30. The second resistor 81 is connected between the source of the MOSFET 16 and a negative-sense input S- of the synchronized rectifying controller 30. The positive-sense input S+ is connected to the ground reference of the power converter and a ground pin GND of the synchronized rectifying controller 30. A supply-voltage pin VCC of the synchronized rectifying controller 30 is connected to the positive end of the power converter output. A timing resistor 31 is connected between an input RT of the synchronized rectifying controller 30 and the ground reference.

[0027] FIG. 6 shows the synchronized rectifying controller 30 according to a preferred embodiment of the present invention. The synchronized rectifying controller 30 comprises comparators 49, 50 and 51, current sources 46, 47 and 48, a NOT-gate 52, an AND-gate 56, an AND-gate 57, two flip-flops 54 and 55 and a single-pulse generator 53. A positive input of the comparator 49 and a negative input of the comparator 50 are

coupled to the detection input DET of the synchronized rectifying controller 30. The current source 48 is connected between the supply voltage pin VCC and the positive input of the comparator 49. A reference voltage V_{R1} supplies a negative input of the comparator 49. A reference voltage V_{R2} supplies a positive input of the comparator 50. The current source 46 is connected from the supply voltage pin VCC to a negative input of the comparator 51. The current source 47 is connected from the supply voltage pin VCC to a positive input of the comparator 51. The positive input and the negative input of the comparator 51 are respectively the positive-sense input S+ and the negative-sense input S- of the synchronized rectifying controller 30. An output of the comparator 49 is connected to a first input D_H of the single-pulse generator 53 and a CLOCK-input of the flip-flop 54. A second input of the single-pulse generator 53 is coupled to the timing resistor 31. An output S₀ of the single-pulse generator 53 is connected to a first input of the AND-gate 56 and a first input of the AND-gate 57. An output of the comparator 50 is connected to a second input of the AND-gate 57, an input of the NOT-gate 52, and a CLOCK-input of the flip-flop 55. An output of the flip-flop 55 is connected to a third input of the AND-gate 57. An output of the comparator 51 is connected to a second input of the AND-gate 56. The flip-flop 54 is reset by an output of the NOT-gate 52. The flip-flop 55 is reset by an output of the AND-gate 56. An input of the flip-flop 54 and an input of the flip-flop 55 are connected to the supply voltage pin VCC. The output of the flip-flop 54, which is also the first output OUT1 of the synchronized rectifying controller 30, generates a first gate-signal to control the MOSFET 15 shown in FIG. 5. The output of the AND-gate 57, which is also the second output OUT2 of the synchronized rectifying controller 30, generates a second gate-signal to control the MOSFET 16 shown in FIG. 5.

[0028] The transformer 11 is a forward transformer. When the PWM signal is logic-high, the primary-side MOSFET 10 will be turned on and the input voltage $V_{\rm IN}$ will be conducted through the primary winding of the transformer 11. The primary winding and the secondary winding will accumulate energy proportionally from the input voltage $V_{\rm IN}$. The voltage of the positive terminal of the secondary winding will begin to risé. Eventually, it will exceed the voltage of the reference voltage $V_{\rm RI}$, causing the comparator 49 to output a logic-high signal. This logic-high signal generated by the comparator 49 will trigger the flip-flop 54. The flip-flop 54 will then output a logic-high first gate-signal to the first output OUT1 of the synchronized rectifying controller 30.

[0029] When the PWM signal goes off, the voltage of the positive terminal of the secondary winding will drop to zero. The comparator 50 will output a logic-high signal to the input of the NOT-gate 52. The NOT-gate 52 will invert this logic-high signal and reset the flip-flop 54 to clear the first gate-signal at the first output OUT1 of the synchronized rectifying controller 30.

[0030] When a high voltage occurs at the positive terminal of the secondary winding, the single-pulse generator 53 will be activated by the output of the comparator 49. This will cause the single-pulse generator 53 to output a pulse-signal S_0 . The resistance of the timing resistor 31 determines a period T_1 of the pulse-signal S_0 . When the voltage at the positive terminal of the secondary winding drops below a level of a reference voltage V_{R2} , the flip-flop 55 will be triggered by the output of the comparator 50. The flip-flop 55 will output a logic-high signal to the third input of the AND-gate 57. When the output of the comparator 50, the output of the flip-flop 55, and the pulse-signal S_0 are all logic-high, the AND-gate 57 will generate a logic-high second gate-signal to the second output OUT2 of the synchronized rectifying controller 30.

[0031] Following the period T_1 , the pulse-signal S_0 will drop to logic-low and disable the AND-gate 57. The output of the AND-gate 57 will be cleared to terminate the on-period of the second gate-signal. The period T_1 introduces a delay time T_d before the start of the next switching signal. Without the delay time T_d , a short-circuit condition could occur during the next switching period if the MOSFET 16 is still turned on. According to the present invention, the period T_1 of the single-pulse generator 53 can be adjusted to determine the precisely turn-off time of the MOSFET 16, ensuring that the MOSFET 16 turns off before next switching period starts.

[0032] FIG. 7 shows the single-pulse generator 53 according to a preferred embodiment of the present invention. The single-pulse generator 53 comprises an operational amplifier (OPA) 60, NOT-gates 69, 70 and 71, an AND-gate 72, a MOSFET 62, a current mirror composed of three MOSFETs 61 and 63, current sources 64 and 65, a capacitor 66, a MOSFET 67 and an OPA 68. A reference voltage V_{R3} is supplied to a positive input of the OPA 60. A negative input of the OPA 60 is coupled to a source of the MOSFET 62 and the timing resistor 31. An output of the OPA 60 is connected to a gate of the MOSFET 62. A drain of the MOSFET 61, a drain of the MOSFET 62, a gate of the MOSFET 61, and a gate of the MOSFET 63 are tied together. A source of the MOSFET 61 and a source of the MOSFET 63 are connected to the supply voltage pin VCC. A drain of the MOSFET 63 is connected to a negative input of the OPA 68 and a drain of the MOSFET 67. The current source 64 is connected between the supply voltage pin VCC and the negative input of the OPA 68. A reference voltage V_{R4} is supplied to a positive input of the OPA 68. The capacitor 66 and the current source 65 are connected in parallel between the drain and a source of the MOSFET 67. The source of the MOSFET 67 is connected to the ground reference. A gate of the MOSFET 67 is

connected to an output of the AND-gate 72. The NOT-gates 69, 70 and 71 are connected in series. An output of the NOT-gate 69 is connected to an input of the NOT-gate 70. An output of the NOT-gate 70 is connected to an input of the NOT-gate 71. An output of the NOT-gate 71 is connected to a first input of the AND-gate 72. A second input of the AND-gate 72 and an input of the NOT-gate 69 are connected to the output of the comparator 49 shown in FIG. 6. An output of the comparator 68 is the output of the single-pulse generator 53, which supplies the pulse-signal S₀.

[0033] When the voltage at the positive terminal of the secondary winding is low, the comparator 49 will output a logic-low signal to the first input D_H of the single-pulse generator 53. This logic-low signal will disable the AND-gate 72. The MOSFET 67 will remain off due to the logic-low signal output from the AND-gate 72. The comparator 60, the MOSFET 62, and the timing resistor 31 will generate a current I_T . The current mirror mirrors the current I_T to a first current I_T , which is coupled with the current source 64 to charge the capacitor 66. The amplitude of the current I_T is given by following equation, where I_T is the resistance of the timing resistor 31:

$$I_T = V_{R3} / R_T \tag{1}$$

[0034] The first current I_1 can be expressed by the following equation, where N_{63}/N_{61} is the geometric ratio of the MOSFETs 63 and 61:

$$I_1 = (N_{63} / N_{61}) \times I_T \tag{2}$$

[0035] Before the voltage across the capacitor 66 exceeds the voltage of the

reference voltage V_{R4} , which provides a threshold voltage for generating the pulsesignal S_0 , the output of the single-pulse generator 53 will remain logic-high. The period T_1 of the single-pulse generator 53 is determined by the charge time of the capacitor 66, which can be expressed by the following equation, where C_{66} is the capacitance of the capacitor 66, I_{64} is the current of the current source 64, and I_{65} is the current of the current source 65:

$$T_1 = \frac{C_{66} \times V_{R4}}{I_{64} + I_1 - I_{65}} \tag{3}$$

[0036] The current sources 64 and 65 are programmable. Increasing the current I_{64} and decreasing the current I_{65} can shorten the delay time T_d . Decreasing the current I_{64} and increasing the current I_{65} can expand the delay time T_d . This allows the delay time T_d to be optimized to compensate for variations to the switching frequency. Such variations can be caused by factors such as temperature, component degradation, etc. The delay time T_d before the start of each switching cycle can be expressed by the following equation, where T is the period of the PWM signal:

$$T_d = T - T_1 \tag{4}$$

[0037] Once the voltage detected from the positive terminal of the secondary winding exceeds the voltage of the reference voltage V_{R1} , the voltage at the first input D_H of the single-pulse generator 53 will become logic-high. This logic-high signal will be supplied to the second input of the AND-gate 72. However, the NOT-gates 69,70 and

71 will delay the signal from the first input D_H of the single-pulse generator 53.

Before the logic-high signal from the first input D_H of the single-pulse generator 53 can propagate through to the first input of the AND-gate 72, the output of the AND-gate 72 will be logic-high for an instant. This will turn on the MOSFET 67 to discharge the capacitor 66. When the delayed signal from the first input D_H of the single-pulse generator 53 finally propagates through to the first input of the AND-gate 72, the MOSFET 67 will be turned off. Then the capacitor 66 will begin to be charged. [0039] Further referring to FIG. 5 and FIG. 6, the resistors 80 and 81 are used to

prevent the flow of an inverse discharge current from the output capacitor 14 to the MOSFET 16. When the capacitor 14 begins to supply an inverse discharge current, it will cause the voltage at the negative-sense input S- to exceed the voltage at the positive-sense input S+. The comparator 51 will output a logic-low signal to disable the output of the AND-gate 56. This will reset the flip-flop 55 and turn off the second gate-signal at the second output OUT2 of the synchronized rectifying controller 30.

[0040] It will be apparent to those skilled in the art that various modifications and variations can be made to the structure of the present invention without departing from the scope or spirit of the present invention. In view of the foregoing, it is intended that the present invention cover modifications and variations of this invention provided that they fall within the scope of the following claims and their equivalents.